

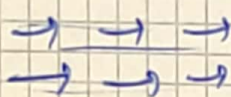
# General Relativity Week 4

Definition: A connection on  $M$  is a map  $\nabla: \Gamma(M) \times \Gamma(M) \rightarrow \Gamma(M)$  which is:

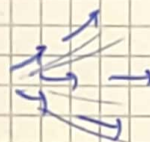
- 1)  $C^\infty(M)$ -linear in 1<sup>st</sup> argument:  $\nabla_{X_1 + f \cdot X_2} Y = \nabla_{X_1} Y + f \cdot \nabla_{X_2} Y$
- 2)  $\mathbb{R}$ -linear in 2<sup>nd</sup> argument:  $\nabla_X (Y_1 + a Y_2) = \nabla_X Y_1 + a \nabla_X Y_2$
- 3) Leibniz rule for 2<sup>nd</sup> argument:  $\nabla_X (f \cdot Y) = X(f) \cdot Y + f \cdot \nabla_X Y$

Note:  $\nabla_X Y|_p$  = "Directional" derivative of  $Y$  at  $p$  in the direction  $X|_p$

• Lie derivative  $L_X Y$  is not tensorial on  $X$  (depends on  $\partial X$ )



vs.



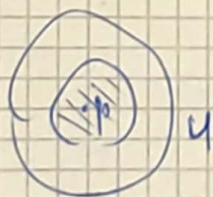
• If  $Y \in \Gamma(M)$   $\nabla Y$  is a  $(1,1)$ -tensor field.

The connection ~~is~~ is "local":

Lemma: Let  $Y \in \Gamma(M)$ ,  $Y|_U = 0$  on an open set  $U$ .

Then  $\forall X \in \Gamma(M)$   $\nabla_X Y|_U = 0$ .

PF:  $\forall p \in U$ , let  $f = 1$  in a neighborhood of  $p$ ,  
 $f = 0$  on  $M \setminus U$ .



Then  $f \cdot Y = 0$  everywhere

$$\Rightarrow \nabla_X (f \cdot Y)|_p = \underbrace{X(f)|_p}_{=0} \cdot Y|_p + f|_p \cdot \nabla_X Y|_p = 0 + 1 \cdot \nabla_X Y|_p = \nabla_X Y|_p = 0 \quad \square$$

So: We can talk about  $\nabla$  "locally" around points

(i.e. only for vector fields defined on open sets, such as coordinate vector fields)



Christoffel symbols: In any local coordinate system,

$$\nabla_{\frac{\partial}{\partial x^i}} \frac{\partial}{\partial x^j} = \Gamma_{ij}^k \frac{\partial}{\partial x^k} \quad \text{or} \quad \Gamma_{ij}^k = dx^k \left( \nabla_{\frac{\partial}{\partial x^i}} \frac{\partial}{\partial x^j} \right)$$

Not a tensor field! - Depends on coordinates (But  $\nabla - \bar{\nabla}$  is a tensor field)

Ex: ~~Other connection~~

Note:

$$(\nabla_x Y)^k = X^i \frac{\partial}{\partial x^i} Y^k + \Gamma_{ij}^k X^i Y^j$$

Ex: Flat connection on  $\mathbb{R}^n$ :

In Cartesian coordinates,

$$(\nabla_x Y)^k = X^i \frac{\partial}{\partial x^i} Y^k$$

(so  $\Gamma_{ij}^k = 0$  in Cart. coordinates,

but not in other coordinate system  
e.g. polar coordinates)

Def: Torsion:  $T(X, Y) = \nabla_X Y - \nabla_Y X - [X, Y]$

(Note:  $\nabla_X^* Y := \nabla_Y X + [X, Y]$  : "Dual" connection)

•  $(1, 2)$ -tensor field

• In coordinates:  $T_{ij}^k = \Gamma_{ij}^k - \Gamma_{ji}^k$

$\nabla$  is torsion free iff  $T \equiv 0 \Leftrightarrow \Gamma_{ij}^k = \Gamma_{ji}^k \Leftrightarrow \nabla_{\frac{\partial}{\partial x^i}} \frac{\partial}{\partial x^j} = \nabla_{\frac{\partial}{\partial x^j}} \frac{\partial}{\partial x^i}$

It suffices to hold  
in one coordinate  
system



We can extend  $\nabla$  to act on tensor fields by the requirement that

$$\bullet \nabla_X (f \otimes h) = (\nabla_X f) \otimes h + f \otimes (\nabla_X h)$$

and  $\bullet \operatorname{tr}(\nabla_X f) = \nabla_X (\operatorname{tr} f)$

For instance, from the above two properties:

For 1-forms: 
$$(\nabla_X \omega)_a = X^i \frac{\partial}{\partial x^i} \omega_a - \Gamma_{ia}^k X^i \omega_k$$

Levi-Civita connection:

Let  $(M, g)$  be a Lorentzian manifold. There exists a unique connection  $\nabla$  such that

1)  $\nabla$  is torsion free:

2)  $\nabla$  respects the metric:

$$X(g(Y, Z)) = g(\nabla_X Y, Z) + g(Y, \nabla_X Z) \quad \forall X, Y, Z \in \Gamma(M)$$

$$(\Leftrightarrow \nabla_X g = 0 \quad \forall X \in \Gamma(M))$$

Construction: In local coordinates:

$$X = \partial_i, \quad Y = \partial_j, \quad Z = \partial_k$$

$$\begin{aligned} \partial_i g_{jk} &= g(\nabla_{\partial_i} \partial_j, \partial_k) + g(\partial_j, \nabla_{\partial_i} \partial_k) \\ &= \Gamma_{ij}^a g_{ak} + \Gamma_{ik}^a g_{aj} \end{aligned}$$

Permuting  $i, j, k$  and using  $\Gamma_{ij}^a = \Gamma_{ji}^a$ :

$$\partial_i g_{jk} + \partial_j g_{ik} - \partial_k g_{ij} = 2 \Gamma_{ij}^a g_{ak} \Rightarrow \Gamma_{ij}^k = \frac{1}{2} g^{kh} (\partial_i g_{jh} + \partial_j g_{ih} - \partial_h g_{ij})$$



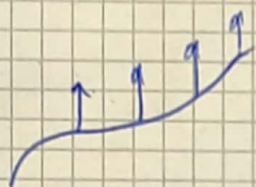
- Rmks:
- Canonical connection
  - Commute with "function of  $g$ "  
e.g. the volume form,  
musical isomorphism!

ie.  $(\nabla X)_2 = \nabla(X_2)$   
 $(X_2 = \text{tr}(g \otimes X))$

So we will write  $\nabla_a X_b$  without specifying if I apply the musical isomorphism before or after differentiation.

Parallel transport:

Let  $\gamma: (a,b) \rightarrow M$  be a smooth curve.



I can consider vector fields along  $\gamma$ :

$$X \in T_\gamma : t \longrightarrow X_t \in T_{\gamma(t)} M$$

Ex:  $\dot{\gamma}$

Note: At points of self intersections of  $\gamma$ ,  
 $X \in T_\gamma$  cannot be extended to  $T(M)$

But always: If I shrink the domain of  $\gamma$  around  $t$   
 so that no self intersection takes place,  
 I can extend  $X \in T_\gamma$  to  $X \in T(M)$   
 (in a non-unique way).

So I can talk about  $\nabla_j X$

For any such extension:  $\nabla_j X|_{\gamma(t)}$  is the same.

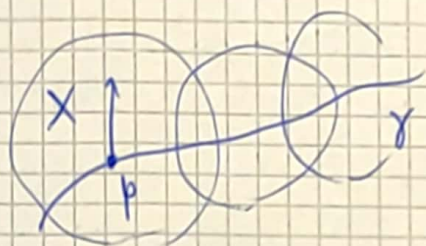


Proof: In local coordinates around  $\gamma(t)$ :

$$(\nabla_{\dot{\gamma}} Y)^k = \dot{\gamma}^i \partial_i Y^k + \Gamma_{ij}^k \dot{\gamma}^i Y^j$$

$\underbrace{\hspace{10em}}_{\frac{d}{dt} Y^k(\gamma(t))}$

$$S_0 = \frac{d}{dt} Y^k + \Gamma_{ij}^k \dot{\gamma}^i Y^j \quad \square$$



Def:  $X \in T_{\gamma}$  is parallel transported if  $\nabla_{\dot{\gamma}} X = 0$ .

$$\forall \xi \in T_p M: \exists! X \in T_{\gamma} \text{ st } \begin{cases} \nabla_{\dot{\gamma}} X = 0 \\ X|_{t=0} = \xi \end{cases}$$

( $p = \gamma(0)$ )

$$(S_0 \quad X|_t = P_{0 \rightarrow t}^{(X)} \xi)$$

PF: In local coordinates:

$$\begin{cases} \frac{d}{dt} X^k + \Gamma_{ij}^k \dot{\gamma}^i X^j = 0 \\ X^k|_{t=0} = \xi^k \end{cases}$$

Linear ODE, unique solution.

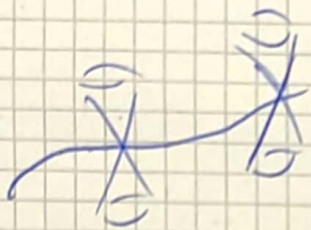
(Covering the curve with a finite number of coordinate charts between  $\gamma(0)$  and  $\gamma(t) \dots$ )



Parallel transport :  $P^{(x)} : T_{\gamma(0)} M \rightarrow T_{\gamma(t)} M$

linear isometry :

$$\nabla_{\dot{\gamma}} \langle X, Y \rangle = 0 \quad \text{if} \quad \nabla_{\dot{\gamma}} X = \nabla_{\dot{\gamma}} Y = 0.$$

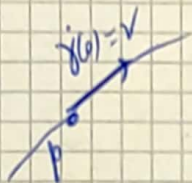


← Sends the light cone to the light cone!

Geodesic :  $\nabla_{\dot{\gamma}} \dot{\gamma} = 0$

In Minkowski: Straight line.

Thm:  $\forall p \in M, \forall v \in T_p M: \exists!$  maximal geodesic  
with  $\gamma(0) = p, \dot{\gamma}(0) = v$



Pf: In local coordinates:  $\ddot{x}^k + \Gamma_{ij}^k \dot{x}^i \dot{x}^j = 0$

So: by existence and uniqueness of solutions  
for ODE ...  $\square$

Rmk: • If  $\gamma_1, \gamma_2$  geodesics and  $\left. \begin{array}{l} \gamma_1(T) = \gamma_2(T) \\ \dot{\gamma}_1(T) = \dot{\gamma}_2(T) \end{array} \right\} \gamma_1 = \gamma_2$   
on their common domain of definition

•  $\nabla_{\dot{\gamma}} \ddot{\gamma} = 0 \Rightarrow g(\dot{\gamma}, \dot{\gamma}) = \text{const}$

So it makes sense to talk about timelike/spacelike/null geodesics



Moreover: If  $X$  is a Killing vector field

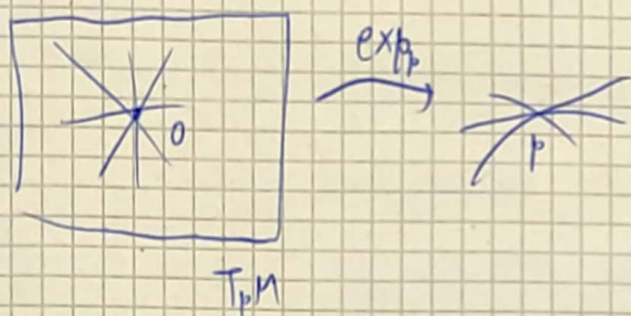
$$\Rightarrow g(X, \dot{\gamma}) \text{ is constant along } \gamma$$

If I have enough symmetries: I can reduce the study of geodesics to a 1<sup>st</sup> order problem.

Exponential map.

→ Geodesic with  $\gamma(0)=p$ ,  $\dot{\gamma}(0)=v$

Let  $\Omega_p = \{v \in T_p M : \gamma_{p,v} \text{ is defined on } [0,1]\}$



Define  $\exp_p: \Omega_p \rightarrow M$

$$\text{by } \exp_p(v) = \gamma_{p,v}(1)$$

- Smooth map (since  $\gamma_{p,v}$  depends smoothly on the initial data)
- $\exp_p(tv) = \gamma_{p,v}(t) = \gamma_{p,tv}(1)$

Lem  $d\exp_p|_{v=0} = \text{id}$

PF: If  $\phi(t) = tv$  (straight line in  $T_p M$ )

$$\underbrace{\frac{d}{dt} (\exp_p(\phi(t)))}_{\dot{\gamma}_{p,v}(t)} \Big|_{t=0} = d\exp_p|_{\phi(0)} (\dot{\phi}(t)) \Big|_{t=0} = d\exp_p|_{v=0} (v)$$

$\dot{\gamma}_{p,v}(t) \Big|_{t=0} = v$  □

So: By ~~inverse~~ inverse function theorem:  $\exp_p$  is a local diffeo around  $v=0$ .



I can use  $\exp_p$  to define local coordinates around  $p$

Normal coordinates around  $p \in (M, g)$

Choose orthonormal frame  $\{e_0, \dots, e_n\}$  in  $T_p M$

$$\text{So } \forall v \in T_p M: \quad v = v^a e_a$$

Then define coordinates  $(x^0, \dots, x^n)$  around  $p$  so that

$$x^a(\exp_p(v)) = v^a \quad \Rightarrow \quad x^a(q) = (\exp_p^{-1}(q))^a$$

In these coordinates:  $\gamma_{p,v}^k(t) = v^k t$  (geodesics through  $p$  are straight lines)

Proposition:

In normal coordinates around  $p$ :  $(p = (0, \dots, 0))$

$$g_{ab}(0) = \eta_{ab}, \quad \partial_k g_{ab}(0) = 0, \quad \Gamma_{ab}^k(0) = 0$$

(But, in general:  $\partial_{ab}^c g_{\mu\nu} \neq 0$ )